

GNSS Module ME31GR02



Datasheet V 1.0.0

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Version Note

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Part Number

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ME31GR02	4NN	

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PRODUCT INTRODUCTION

1.1 General Description

The ME31GR02 is a single-frequency, full-constellation satellite positioning GNSS module. Thanks to the multi-constellation RF front-end architecture, all four major GNSS constellations (GPS, Beidou, Glonass, and Galileo) can be received at the same time, with simultaneous support for both QZSS and SBAS satellites, resulting in a receiver with excellent sensitivity and acquisition capabilities, and excellent interference suppression characteristics that enable the receiver to achieve reliable even under difficult signal conditions positioning. The multi-system combination greatly increases the number of visible satellites when traveling in dense urban canyon environments, reducing the time to first fix and improving positioning accuracy, even in harsh environments.

The ME31GR02's superior positioning performance makes it ideal for industrial and consumer applications such as vehicle locators, two-wheeler positioning, shared motorcycle, T-Box, in-car navigation, transportation sector (e.g., industrial vehicles, operational vehicle supervision), and inspection operations.

1.2 Key Parameters

ME31GR02 Parameters					
Operating Frequency	GPS/QZSS L1 C/A: 1575.42±1.023 MHz BDS B1I: 1561.098±2.046 MHz B1c: 1575.42±16.368 MHz GLONASS G1: 1598.063 -1605.375 MHz GALILEO E1: 1575.42±2.046 MHz QZSS L1 C/A: 1575.42±1.023 MHz SBAS L1 C/A: 1575.42±1.023 MHz				
Sensitivity1	Cold start: -148dBm; Recapture: -159dBm; Track: -165dBm;				
First Positioning Time1	Cold start: ≤28s; Hot start: 1s;				
Positional Accuracy2	open sky: <1.5 m CEP				
Velocity Accuracy2	<0.05 m/s				
Time Accuracy2	20ns				
Operating Temperature	Operating temperature: -40°C to +85°C				
Refresh Rate	Default GNSS: 1Hz, maximum 5Hz supported				
Baud	Main Serial Port 115200bps (factory default)				
RTCM Differential Output	RTCM3.x exports				
Supported Protocols	NMEA 0183 protocols Ver. 4.0/4.1, RTCM 3.x				

7 TECHNICAL INFORMATION

2.1 Supporting Constellations

The ME31GR02 can simultaneously receive L1-band satellite signals supporting GPS, BDS, GLONASS, GALILEO, QZSS, and Satellite Based Augmentation System SBAS (WAAS, EGNOS, GAGAN, MSAS) due to its multi-constellation RF front-end architecture.

2.2 Satellite-based Augmentation System (SBAS)

The ME31GR02 supports the reception of SBAS broadcast signals. These systems supplement GNSS data with other regional or wide-area GPS augmentation data. The system broadcasts distance correction and integrity information via satellite, which can be used by GNSS receivers to improve the accuracy of results. SBAS satellites can be used as add-on satellites for ranging (navigation) to further improve availability. The following SBAS types are supported: GAGAN, WAAS, EGNOS and MSAS.

Typology	Satellite Navigation System	Operation and Maintenance Country/region
	GPS	United States of America
Master Naviga-	Beidou (BDS)	China
tion System (GNSS)	GLONASS	Georgia
	GALILEO	EU
local Navigation	QZSS	Japanese
system	NAVIC/IRNSS	India
	WASS	United States of America
Star-based Wide	EGNOS	EU
Area Strengthen- ing (SBAS)	MSAS	Japanese
	GAGAN	India

2.3 Quasi-Zenith Satellite (QZSS)

The Quasi-Zenith Satellite System (QZSS) is a navigation satellite overlay system for the Pacific Ocean covering Japan and Australia that transmits other GPS L1C/A signals. The module is capable of receiving and tracking these signals simultaneously with GPS, which improves availability and maintains positioning especially in poor signal conditions such as urban canyons.

2.4 Satellite Enhancement Code Differential DGNSS

The ME31GR02 supports the use of the code difference function, D-GNSS, with access to pseudo-range correction information in RTCM 2.3 or user-defined formats. The ME31GR02, used as a mobile station, will attempt to provide the best possible positioning accuracy depending on the correction data received. Upon receipt of the RTCM message input stream, it will immediately enter differential mode. Upon entering D-GNSS mode, an improvement in positioning accuracy can be expected. D-GNSS is a differential system where the mobile station uses reference data from a reference station. If the RTCM correction function is not available, it will operate as a stand-alone precision receiver for GNSS star-based or single-point positioning.







2.5 AGPS

The ME31GR02 supports for the AGPS Accelerated Positioning Scheme. Please refer to "AGPS Integration Guide.pdf" for specific usage methods.

2.6 Crystal Oscillators

The ME31GR02 uses TCXO to allow weak signal acquisition, resulting in faster start-up and re-acquisition times.TCXO allows the product to ensure that it is stable and immune to frequency interference over its entire operating range (-40° to + 85°C), making it a positioning module with reliable positioning.

2.7 Real Time Clock (RTC)

The RTC is driven by a 32 kHz oscillator using an RTC crystal. If the mains voltage fails, some parts of the receiver will shut down, but the RTC will still operate to provide a timing reference for the receiver. This mode of operation is called "hardware backup mode" and allows all relevant data to be saved in backup RAM for later hot-booting.

2.8 Power System

The ME31GR02 module is available in full operating mode and battery backup mode.

Full operation mode: All power supplies are normally supplied and the module is in full operation mode for normal signal reception and interpretation.

Battery Backup Mode: The module requires very little current (~40uA) to maintain the RTC clock and backup RAM.

2.9 Working Mode

The ME31GR02 supports two power consumption modes, Sleep mode and Active mode. It is possible to switch from Active mode to Sleep mode through software and hardware.

Active mode: Normal operation mode where the DSP core is active and all peripherals are available.

Sleep mode: In this mode, the Soc DSP core, all digital logic (except the RTC Always-On logic), and major portions of the analog/RF circuits are stopped and powered down so that total current can be minimized. In this mode, only GPIOs (serial ports) or RTC timers can wake up the system to Active mode.

In Sleep mode, the BeiDou reference time will run in the RTC timer. The ephemeris and other BeiDou data will be saved to flash periodically for fast startup. If AGNSS/AGPS is available, the time and ephemeris will be downloaded to the Soc chip, so there is no need to switch to Sleep mode if AGNSS/AGPS is available or if you don't care about the hot start TTFF, just don't provide the backup power supply and turn off the VCC main power supply when you don't need to use the positioning function.

ME31GR02 in software mode, when the module receives the host hibernation command and switches from Active mode to Sleep mode, the system shall keep power supply state. After entering Sleep mode, the VCC main power can be further turned off to save power, but at this time, it is necessary to ensure that V_BACKUP is in the power supply state.

In hardware mode, if the module is in Active mode, VCC is powered off and V_BACKUP remains active high, ME31GR02 will automatically switch to Sleep mode. When the module is in sleep mode, all IOs connected to the module should remain in a low or high impedance state. If any of the connected IO pins present are in a high state, the leakage of the ME31GR02 sleep circuitry will increase. When the ME31GR02 wakes up from sleep mode (triggered by an RTC timer or GPIO), the VCC main power supply must remain active.

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3 ELECTRICAL SPECIFICATION

3.1 Absolute Maximum Rating

Notation	Parameters	Minimum Value	Maximum Value	Unit
VCC	Mains voltage	-0.5	3.63	V
VBAT	Backup power supply voltage	-0.5	3.63	V
VI-max	I/O Pin Input Voltage	-0.5	3.63	\vee
Vhbm	ESD Contact	-	2000	V
T-storage	Storage temperature	-40	+85	°C
T-solder	Reflow temperature		250	Ĉ

Pressurizing the equipment beyond the "Absolute Maximum Rating" may cause permanent damage. The above figures are pressure ratings only. Products are not overvoltage or reverse voltage protected. If necessary, voltage spikes exceeding the supply voltage specifications listed in the table above must be limited to the specified range using an appropriate protection diode.

3.2 DC Characteristics

Notation	Parameters	Minimum Value	Typical Value	Maximum Value	Unit
VCC	Mains voltage	2.0	3.3	3.6	\vee
VBAT	Backup power supply voltage	2.5	3.3	3.6	\vee
IABCmax	ANT_BIAS Maximum operating current		3.3	50	mA
Tenv	Operating temperature	-40	25	85	°C

3.3 Power Wastage

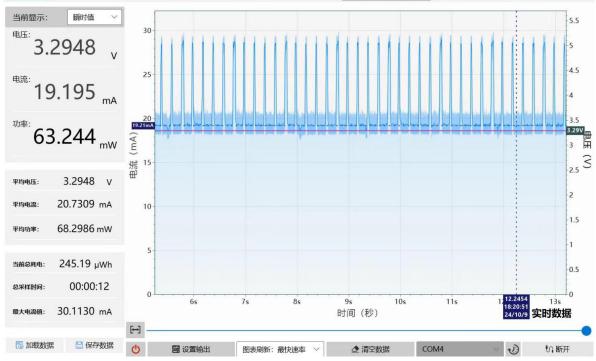
Notation	Parameters	Measurement Pins	Typical Value	Unit		
ICCRX1 ^[1]	capture phase	VCC [2]	21	mA		
ICCRX2 ^[1]	tracking stage	VCC [2]	19	mA		
ICCDBM	hibernation	VBAT ^[3]	11	uA		
	Remarks: * [1] Under open sky, GNSS, L1 band, tracking 32 satellites, successful positioning * [2] Condition: VCC=3.3V, room temperature, all pins dangling * [3] Condition: VBAT=3.3V, room temperature, all pins dangling					

All of the above specifications are at 25°C ambient temperature. Extreme operating temperatures can seriously affect specification values. Applications operating near temperature limits.

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The values in the table are for customer reference only and are intended as examples of typical power requirements. Values are characterized as samples and actual power requirements will vary depending on the firmware version used, external circuitry, number of satellites tracked, signal strength, type of activation as well as time, duration, and test conditions.

The measured values of the capture phase current are as follows:



3.4 Antenna Gain Requirements

Since the ME31GR02 has built-in LNA to support passive GNSS antennas, external active antenna gain is noted to be controlled.

Notation	Parameters	Min	Max	Unit	
RFgain	Input Gain	0	30	dB	

4 PACKAGE DEFINITION

4.1 Module Pin Definitions

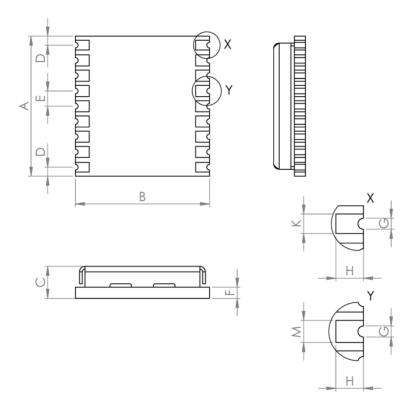
The ME31GR02 is available in the industry's most common 10*10mm, LCC-18pin package, defined as follows:

10	GND	RESET	9
11	RF_IN	vcc	8
12	GND	NC	7
13	NC ME31GR02	V_BCKP	6
14	VCC_RF TOP VIEW	NC	5
15	NC	PPS	4
16	NC	RXD	3
17	NC	TXD	2
18	NC	GND	1
	-		•

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Functionality	y Name	Number	Signal Ty	pe Description
	VCC	8	Power	Mains Power-Input. Ensure that the power input is clean and stable.
power supply	V_BCKP	6	Power	Backup Power Input. It is recommended to connect the backup power supply voltage to this pin in order to position the module for hot and warm start functions. If no backup power is available, V_BCKP can be connected to the main power supply or left dangling.
	GND	1,10,12	GND	Ensure that all GND pins on the module are well grounded.
Antennae	RF_IN	11	Ι	Antenna input, impedance 50Ω
Antennde	VCC_RF	14	0	External active antenna power supply output 3.3V
	TXD	2	0	UART output, TTL level, GNSS_TX
serial port	RXD	3	Ι	UART input, TTL level, GNSS_RX
/10	PPS	4	0	Seconds pulse signal. 3.3V level. Suspend if not used.
	RESET	9	Ι	Reset signal, reset low. Suspension is recommended.
Else	NC	5,7,13~18	-	NC, no definition, please hover

4.2 Mechanical Dimensions



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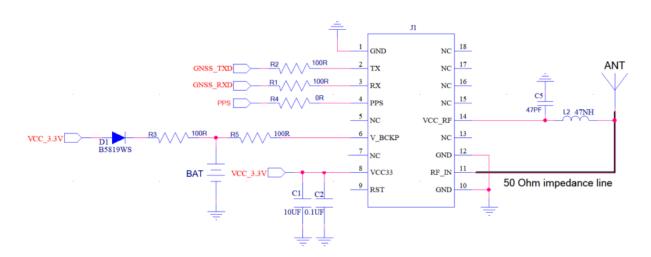
Serial Number	Minimum (mm)	Typical Values (mm)	Maximum Value (mm)
А	10.4	10.5	10.8
В	9.5	9.7	9.9
С	1.9	2.0	2.2
D	0.55	0.8	0.95
E	1.0	1.1	1.2
F	0.5	0.6	0.7
G	0.4	0.5	0.6
Н	0.7	0.8	0.9
К	0.7	0.8	0.9
М	0.8	0.9	1.0

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5REFERENCE DESIGN

5.1 Schematic Design

The reference design of ME31GR02 is shown below. When connecting the active antenna, please make sure that the 47nH inductor at L2 position is in the SMD state, which is used to power the active antenna, and the characteristic impedance from RF_IN pin to the antenna connector is 50Ω . When applying the antenna, the performance of the antenna is crucial to the system, and it is important to ensure the technical parameter of the dual-band high-precision antenna.Pin6 can be connected to the V_BCKP backup power supply, which supports the hardware hot-start.



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5.2 Layout Notes

(1) Decoupling capacitors are placed close to the module power supply pins, and ensure that the power supply alignment width is more than 0.5mm;

(2) No wires are allowed to be routed at the bottom of the module patch;

(3) The RF alignment between the RF port of the module and the antenna interface should be at least 0.2mm~0.3mm, and the coplanar waveguide impedance model should be adopted, and the spacing between the alignment and the ground copper skin should be controlled to be about 1 times of the spacing, and the impedance should be guaranteed to be 50Ω ;

(4) The alignment from the module RF port to the antenna connector references Layer 2 ground and ensures that the Layer 2 ground plane is relatively complete;

(5) Modules should not be placed near sources of interference, such as communication module antennas, RF alignments, crystal oscillators, large inductors, and high-frequency digital signal lines.

5.3 Power Supply

The ME31GR02 Positioning Module is equipped with two power supply pins: VCC and V_BCKP. the main power supply is fed to the module via the VCC pin, and the backup power supply is fed to the module via the V_BCKP pin. To ensure the positioning performance of the module, the ripple of the module power supply should be controlled as much as possible. It is recommended to use an LDO supply with a maximum output current greater than 100mA. If the module's main power supply is disconnected, the system will provide power to the RTC and the Battery Backup RAM (BBR) through V_BCKP.

Therefore, even if the main power supply is disconnected, the ephemeris data can still be retained with the backup power supply and can be used for a hot or warm start when the system is powered up again. If no backup power supply is connected and no data is received by the module, then the system will perform a cold start when it is powered up again. Note: If there is no backup power available, connect the V_BCKP pin to the VCC mains or leave it idle.

5.4 Antenna

The ME31GR02 has a built-in low noise figure LNA and SAW. it is recommended to use an active antenna with a gain of less than 25dB and a noise figure of less than 1.5dB. The module supplies power to the external active antenna via RF_IN. If the active antenna cable is long, an active antenna with at least 15dB of gain is required to compensate for line losses. To maintain ground integrity, it is recommended that no or as few wires as possible be routed under the module.

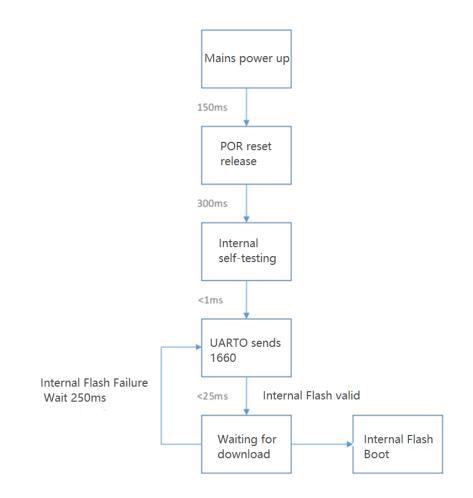
5.5 Serial Port Communication

Provide one way TTL level universal asynchronous transceiver (UART), the data format is: 1 bit start bit, 8 bit data bit, 1 bit stop bit, no parity bit, the default baud rate is 115200bps. after the module is normally powered on, the serial port will automatically send NMEA data. The host computer can set the module working mode and baud rate through the serial port. When this module is used in some specific application scenarios, the main power of the module may be turned off due to the power saving strategy, so as to further reduce the power consumption.

In this case, in order to avoid the high level of the serial port affecting the normal operation of the module, it is strongly recommended to disconnect the serial port connection at the same time when disconnecting the main power supply, or set the serial port to the state of input state + pull-down resistor or high resistance state + pull-down resistor.

5.6 Startup Process

The module startup process is as follows:



6 SOFTWARE PROTOCOL

6.1 NEMA0183 Pact

The NMEA protocol is an ASCII based protocol where the record starts with a \$ and ends with a carriage return/line feed character, and the checksum of the NMEA message, which can be used to detect corrupted data transmission. The frame structure is as follows:

Start Character	Checksum Range			Checksum	End Flag
\$	Talker ID	Message ID	[,field 0][,field N]	*Checksum	<cr><lf></lf></cr>

The NEMA message output for the ME31GR02 is shown in the following table:

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NMEA Record	Description	Default	
GNGGA	Global positioning system fixed data	Υ	
GNGLL	Geographic position—latitude/longitude	Y	
GNGSA	GNSS DOP and active satellites	Υ	
GPGSV	GNSS satellites in view for GPS	Υ	
GLGSV	GNSS satellites in view for GLONASS	Y	
BDGSV	GNSS satellites in view for BD	Υ	
GAGSV	GNSS satellites in view for Galileo	Υ	
GNRMC	Recommended minimum specific GNSS data	Y	
GNVTG	Course over ground and ground speed	Υ	
GNZDA	Date and Time	Ν	
GNGST	Position error statistics	Υ	
GNHDT			

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6.2 Example Data

Serial port data within 1 second of the example after positioning: \$GNGGA,065826.00,2242.2940466,N,11401.6896089,E,1,31,0.5,133.811,M,0.000,M,,*4B \$GNGSA,A,3,02,04,07,08,09,16,21,30,194,195,196,199,1.0,0.5,0.8,1*34 \$GNGSA,A,3,,,,,1.0,0.5,0.8,1*3D \$GNGSA,A,3,01,02,03,04,06,07,09,10,12,16,24,26,1.0,0.5,0.8,4*33 \$GNGSA,A,3,29,35,59,60,,,,,1.0,0.5,0.8,4*3F \$GNGSA,A,3,,,,,1.0,0.5,0.8,2*3E \$GNGSA,A,3,02,08,15,,,,,1.0,0.5,0.8,3*31 \$GPGSV,5,1,17,01,00,000,40,02,55,156,45,04,20,195,37,07,49,321,42,1*61 \$GPGSV,5,2,17,08,56,010,43,09,29,237,40,16,17,077,37,21,61,126,45,1*6D \$GPGSV,5,3,17,27,00,000,38,30,18,320,34,194,56,056,42,195,60,101,43,1*60 \$GPGSV,5,4,17,196,21,165,39,199,60,149,37,43,00,000,43,56,00,000,45,1*6B \$GPGSV,5,5,17,57,00,000,41,,,,,,1*55 \$BDGSV,6,1,21,01,46,125,43,02,46,234,39,03,61,189,43,04,32,111,39,1*71 \$BDGSV,6,2,21,06,72,187,43,07,62,319,41,09,79,264,42,10,56,298,40,1*71 \$BDGSV,6,3,21,12,26,215,39,16,70,184,45,24,17,318,37,26,61,353,45,1*7D \$BDGSV,6,4,21,29,19,038,40,35,80,037,47,38,00,000,37,39,00,000,45,1*75 \$BDGSV,6,5,21,40,00,000,43,44,00,000,46,45,00,000,46,59,49,131,45,1*74 \$BDGSV,6,6,21,60,42,238,43,,,,,,1*48 \$BDGSV,3,1,09,24,17,318,34,26,61,353,41,29,19,038,34,35,80,037,43,2*71 \$BDGSV,3,2,09,38,00,000,35,39,00,000,42,40,00,000,40,44,00,000,42,2*79 \$BDGSV,3,3,09,45,00,000,42,,,,,,,2*48 \$GAGSV,1,1,03,02,33,066,39,08,24,204,37,15,36,176,39,...,7*4F \$GNVTG,0.00,T,,M,0.00,N,0.00,K,A*23 \$GNRMC,065826.00,A,2242.2940466,N,11401.6896089,E,0.00,0.00,300124,,,A,V*39 \$GNGST,065826.00,,,,,0.93,0.74,1.65*7D \$GNGLL,2242.2940466,N,11401.6896089,E,065826.00,A,A*70

6.3 Example of an actual star search



6.4 Common Commands

CMD TYPE	CMD Example:
Hot start	\$POLCFGRESET,0
Cold start	\$POLCFGRESET,1
Baud rate 115200	\$POLCFGPRT,115200,0
Baud rate 9600 (too many satellites may congest the serial port)	\$POLCFGPRT,9600,0
Turn off GSV output	\$POLCFGMSG,0,2,0
Turn off GSA output	\$POLCFGMSG,0,1,0
Turn off GLL output	\$POLCFGMSG,0,13,0
Turn off GST output	\$POLCFGMSG,0,12,0
Turn off VTG output	\$POLCFGMSG,0,3,0
Sleep mode (can be woken up after receiving any data on the serial port)	Hex directives: 42 4b 51 05 00 03 00 08 00 00 00 00 00 00 00 00

Remarks:

1. All text format control commands should add Carriage Return (CR) and Line Feed (CF);

2. All configurations must be ended with a save command. Unsaved software configurations will become invalid after the module's main power supply VCC is powered on again;

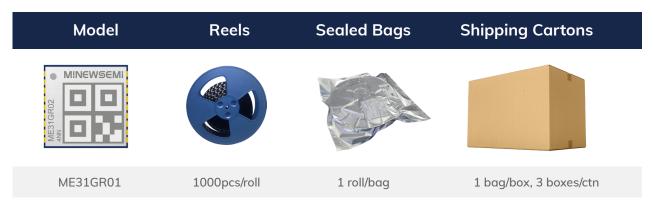
3. Since ME31GR01 has a built-in Flash storage unit, the saved data configuration can remain effective after power failure;

4. A high refresh rate may require a larger baud rate, such as 115200 or higher to avoid serial port data congestion.

PACKAGING AND PROTECTION

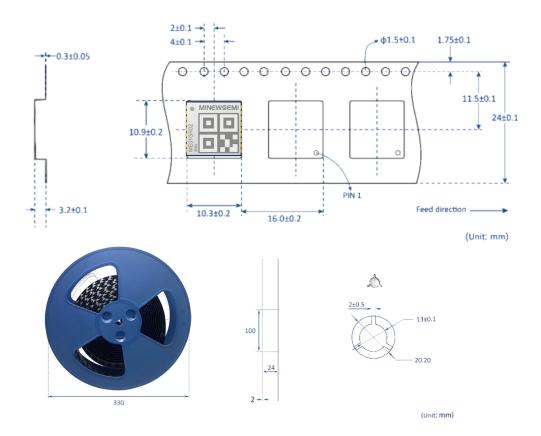
7.1 Wrap

The ME31GR02 is humidity and static sensitive. During packaging and transportation of the product, be sure to follow the handling requirements and take appropriate precautions to minimize product damage. The following table shows the standard packaging structure for transportation of the product.



7.2 Carrier Belts and Trays

The ME32GR02 is supplied on a reel (consisting of a tape and reel) and packaged in a ziplock bag with an anti-static effect to meet the customer's needs for efficient production, batch installation and removal. The following picture shows the dimensional details of the tape reel.



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7.3 Stockpile

In order to prevent the product from moisture and electrostatic discharge, the sealed bag of the product is equipped with desiccant and humidity indicator card, which allows the user to know the humidity condition of the environment in which the product is located. The product has a moisture sensitivity rating of MSL3.

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7.4 ESD Protection

The GNSS positioning module contains highly sensitive electronics and is an electrostatic sensitive device (ESD). Please note the following precautions, as failure to follow these precautions may result in serious damage to the module!

Ground yourself before patching the antenna. Do not touch any charged capacitors and other devices (e.g., antenna patch ~10 pF; coaxial cable ~50 -80 pF/m; soldering iron) when bringing out the RF pin;

To prevent electrostatic discharge, do not expose the antenna area; if exposed by design, take appropriate ESD precautions and do not touch any exposed antenna area;

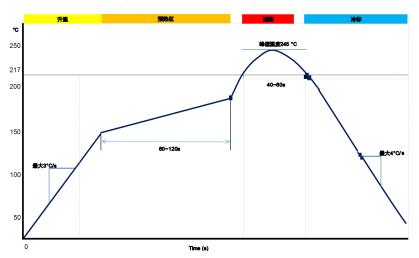
Be sure to use an ESD safe soldering iron when soldering RF connectors and antenna patches.

Add ESD diode to RF input to prevent ESD; add ESD diode to UART interface.



7.5 Production Requirements

The recommended welding temperature profile is shown below:



In order to prevent the module from falling off during soldering, please do not design the module to be soldered on the back of the board, and it is better not to go through two soldering cycles.

The setting of soldering temperature depends on many factors in the product factory, such as the nature of the motherboard, paste type, paste thickness, etc. Please also refer to the relevant IPC standards and paste specifications.

Due to the relatively low temperature of leaded soldering, please prioritize other components on the board if using this soldering method. The openings of the stencil should meet the customer's own product design requirements and inspection specifications, and the thickness of the stencil is recommended to be 0.15mm.





8 ORDERING INFORMATION

8.1 Ordering Model

Ordering Model	Product Name I	Default Baud Rate	Feature	Default Satellite Reception Frequency	Physical Interface
ME31GR02	Single-frequency full-system satellite position- ing module	115200	single-frequency full constellation	GPS/BDS/GLO/GAL/ QZSS, Support B1C	10*10, LCC18

9 STORAGE CONDITIONS

- Please use this product within 6 months after signing up for it.
 - \bullet This product should be stored without opening the package at an ambient temperature of 5~35°C and a humidity of 20~70%RH.
 - This product will be stored for more than 6 months after receipt. They must be confirmed before use.
 - Products must be stored in non-corrosive gases (CI2, NH3, SO2, NOx, etc.).
 - To avoid damage to the packaging materials, no excessive mechanical impact shall be applied, including but not limited to sharp objects adhering to the packaging materials and products falling.

• This product is suitable for MSL3 (based on JEDEC standard J-STD-020).

- After opening the package, the product must be stored under conditions of \leq 30°C/<60%RH. It is recommended to use it within 168 hours after opening the package.
- When the color of the indicator in the package changes, the product should be baked before welding.

● When exposed to (≥168h@30℃/60%RH) conditions, the recommended baking conditions:

1. 120 +5/-5[°]C, 8 hours, 1 time

Products must be baked individually on heat-resistant trays because the materials (base tape, roll tape and cover tape) are not heat-resistant and the packaging materials may deform when the temperature is 120°C; 2.90°C +8/-0°C, 24 hours, once

The base tape can be baked together with the product at this temperature, Please pay attention to even heating.

10 HANDLING CONDITIONS

• Be careful in handling or transporting products because excessive stress or mechanical shock may break products.

• Handle with care if products may have cracks or damages on their terminals. If there is any such damage, the characteristics of products may change. Do not touch products with bare hands that may result in poor solder ability and destroy by static electrical charge.

MINEWSEM

Cognizant of our commitment to quality, we operate our own factory equipped with state-of-the-art production facilities and a meticulous quality management system. We hold certifications for ISO9001, ISO14001, ISO27001, OHSA18001, BSCI.

Every product undergoes stringent testing, including transmit power, sensitivity, power consumption, stability, and aging tests. Our fully automated module production line is now in full operation, boasting a production capacity in the millions, capable of meeting high-volume production demands.

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13 RELATED DOCUMENTS

- MinewSemi_Product_Naming_Reference_Manual_V1.0 https://en.minewsemi.com/file/MinewSemi_Product_Naming_Reference_Manual_EN.pdf
- MinewSemi_Connectivity_Module_Catalogue_V2.0 https://en.minewsemi.com/file/MinewSemi_Connectivity_Module_Catalogue_EN.pdf



For product change notifications and regular updates of Minewsemi documentation, please register on our website: www.minewsemi.com

MINEWSEMI



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