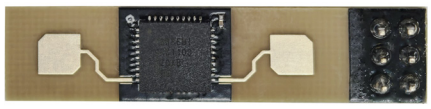
MINEWSEMI

24GHz mmWave Radar Module

ME73MS03



Datasheet

V 1.0.0

Version Note

Version	Details	Contributor(s)	Date	Notes
1.0.0	First edit	Vincle	2025.12.25	

Part Number

Model	Hardware Code
ME73MS03	-

Click the icon to view and download the latest product documents electronically.
https://en.minewsemi.com/file/ME73MS03_Datasheet_C_EN.pdf

ME73MS03

Small size, low power consumption, high sensitivity, cost-effective, micro-motion detection, human presence detection

ME73MS03 is a compact, low-power, high-sensitivity, and cost-effective millimeter-wave radar module based on the SGR SoC. It features an ARM Cortex-M4 MCU operating at 108 MHz. Its efficient data processing ensures detection sensitivity and accuracy, unaffected by environmental factors such as dust, light, and fog, and boasts a maximum detection range of 9 meters, 6-meter static motion detection range.

FEATURES

- FMCW
- High sensitivity
- High cost performance
- Small size

KEY PARAMETERS

ME73MS03			
Working Frequency	24~24.25GHz	**Antenna**	PCB
Module Size	30x7mm	**Detection Distance**	0.5 ~ 9m
Azimuth Coverage	±60°	**Pitch Angle Coverage**	±60°
Transmitting and Receiving Current	64mA	**Avg Current**	19mA
Firmware	HEX command firmware	**Data Interface**	UART

APPLICATIONS

Smart home people detection

Street lighting radar system

Courtyard and indoor security-people detection

Industrial control radar sensor

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1 MODULE DESCRIPTION

1.1 Module Function Description

No.	Function	Details
1	Static Maintenance	Detectable micro-motion targets
2	Motion Sensing	Area personnel motion detection

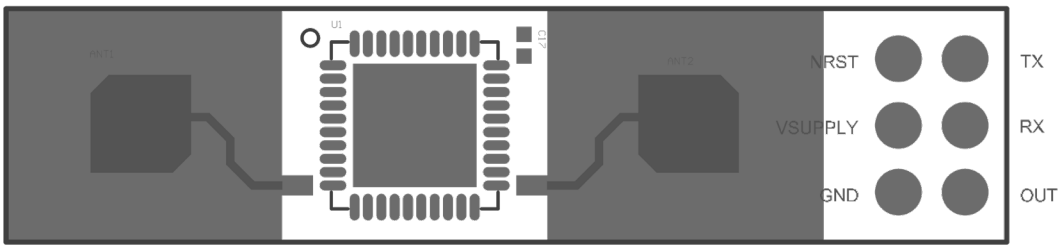
1.2 Module Features

No.	Function	Details
1	Installation Scene	The product detection distance: 0.5~9m. （Note: The detection distance is related to factors such as installation environment, human body volume, relative angle, and movement range. The above parameters are the test results of our company. Under different test conditions, the actual test results shall prevail）
2	Unaffected by the Environment	Unaffected by temperature, humidity, dust, light, noise, etc.
3	Wall Mount	Linear motion detection up to 9 meters, presence detection up to 6 meters.

2 ELECTRICAL SPECIFICATION

Parameter	Value	Notes
Operating Voltage	3.0 ~ 3.5V	To ensure RF operation, the power supply voltage is 3.3V
Operating Temperature	-40℃~+85℃	Storage temperature: -40℃~+125℃
Avg Current	19mA	
Peak power consumption	0.21W	
Module Dimensions	30*7mm	
Quantity of IO Port	3	TX, RX, OUT

3 PIN DESCRIPTION

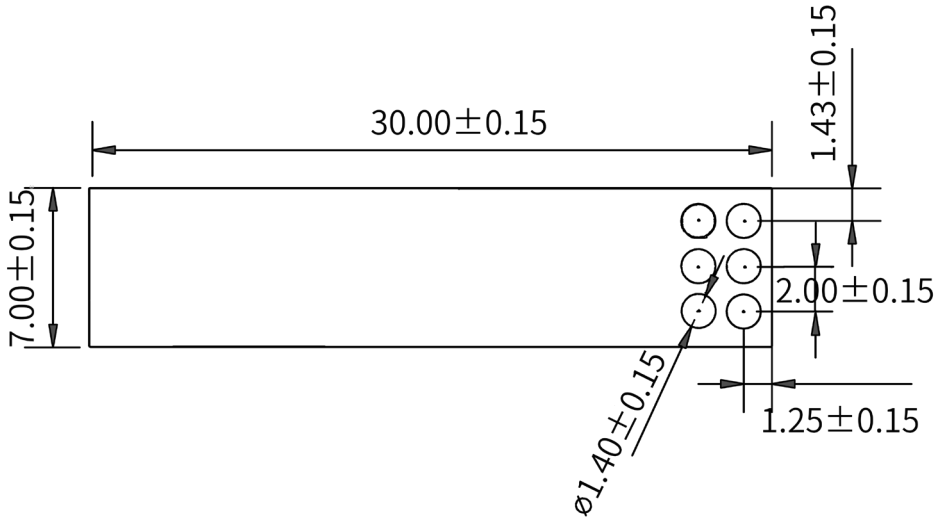


(TOP View)

4 PIN DEFINITION

Symbol	Type	Definition
TX	Serial port TXD	Serial port sending interface
RX	Serial port RXD	Serial port receiving interface
OUT	IO output	Level output interface, high level is valid
GND	Grounding	Ground, negative pole of power supply
VSUPPLY	Power supply	Power supply 3.3V, use this pin for power
NRST	Reset	Module reset pin

5 MECHANICAL DRAWING



* (Default unit: mm Default tolerance: ±0.15)

6 DEBUG CONFIGURATION

6.1 Debug Wiring

The module can be connected to terminals VSUPPLY, GND, OUT (output), RX, TX, and can display configuration parameters and target status information through the serial port. According to the module pin definition diagram, the module's power supply VSUPPLY, ground GND, serial port TX, serial port RX can be connected to the corresponding pins of the serial port board.

6.2 Debug Instructions

Hexadecimal sending and receiving, support online modification and saving of parameters

- **Communication supports UART protocol**

  Baud rate: 115200
  Data bits: 8
  Stop bits: 1
  Parity: none

- **Frame structure definition**

1.Frame header, 2 bytes

Upper computer sends, radar receives: 0x55 0x5A
Radar sends, upper computer receives: 0x55 0xA5

2.Data length, 2 bytes, high byte first, low byte last

Length = function code + command + data + checksum

3.Function code, 1 bytes

Read: 0x0
Write: 0x1
Passive reporter: 0x2
Active reporter: 0x3

The read and write commands are for the upper computer to send instructions to the radar, and the report command is for the radar to send information to the upper computer.

4.Command code

Command code 1 is the function classification, command code 2 is the specific function

5.Data

N Bytes

6.Checksum, 1 Bytes

The lower 8 bits of the sum of all data before the checksum in uint8_t format.

⚠ Note: Data format description: All multi-byte parameters are transmitted in big-endian format.

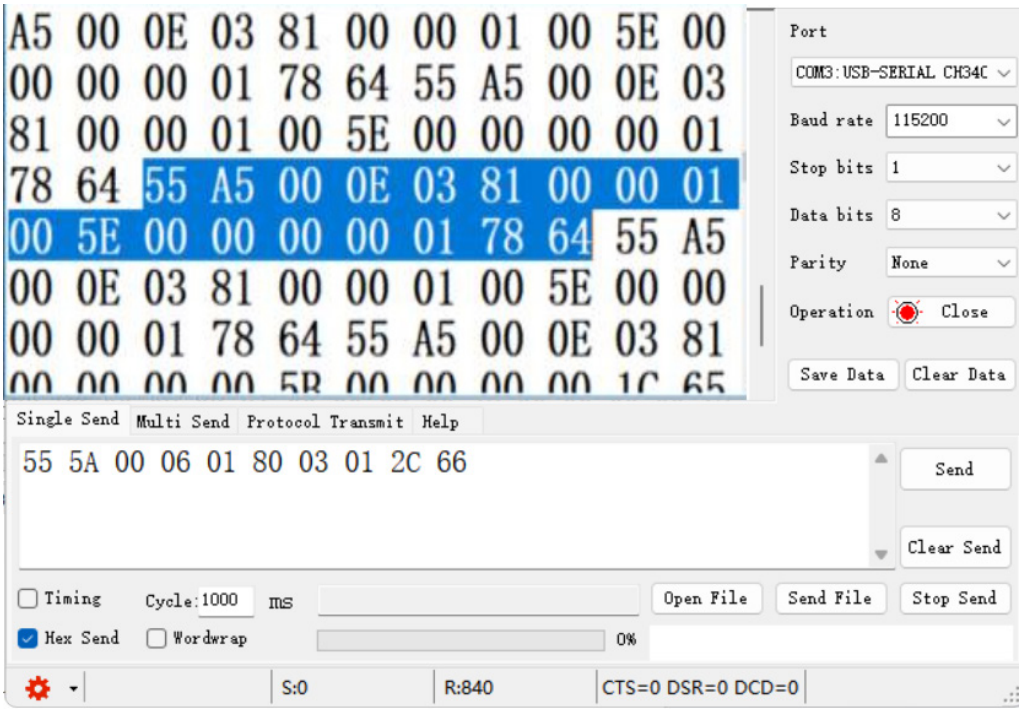
- **Radar Output Data Format**

	Head	Packet Len	Func code	CMD	Data	Sum
Receiving	55 A5	00 0E	03	81 00	Data[0]~Data[9]: Detected target information	SUM

Data Format Description			
Setting/ Receiving	Data[0]		Target ID Number: 8-bit unsigned integer
	Data[1]		Target status: 8-bit unsigned integer; 0: Nobody, 1: Indicates movement body， 2: Indicates existence body
	Data[2]	Data[3]	Distance：16-bit unsigned integer, unit: cm
	Data[4]	Data[5]	Speed：16-bit signed integer, unit: cm/s
	Data[6]		Direction cosine：8-bit signed integer, unit: degrees
	Data[7]		Pitch：8-bit signed integer, unit: degrees
	Data[8]	Data[9]	Signal strength: 16-bit unsigned integer

The radar detection results are reported actively. In the next page, we will give an example to illustrate the radar output information.

Example 1: Read target information



The one marked on the figure is a complete received message:
55 A5 00 0E 03 81 00 00 01 00 5E 00 00 00 00 01 78 64
Target ID: 8th byte 0x00
Movement status: 9th byte 0x01, detected movement body
Target distance: 10th ~11th bytes 0x00 0x5E, converted to decimal is 94
Target signal strength: 16th ~17th bytes 0x01 0x78, converted to decimal is 376
Checksum: 18th byte
In conclusion, detected movement target, target distance is 0.94 meter, signal strength is 376.

Radar parameter configuration and reading commands

OTA online upgrade	Send	55 5A 00 04 01 20 01 D5
	Receive	55 A5 00 04 02 20 01 21
Restore to default parameters	Send	55 5A 00 04 01 20 02 D6
	Receive	55 A5 00 04 02 20 02 22
Save all parameters to flash	Send	55 5A 00 04 01 20 04 D8
	Receive	55 A5 00 04 02 20 04 24
Get the software version	Send	55 5A 00 04 00 00 01 B4
	Receive	55 A5 00 11 02 00 01 DATA1~DATA13 SUM

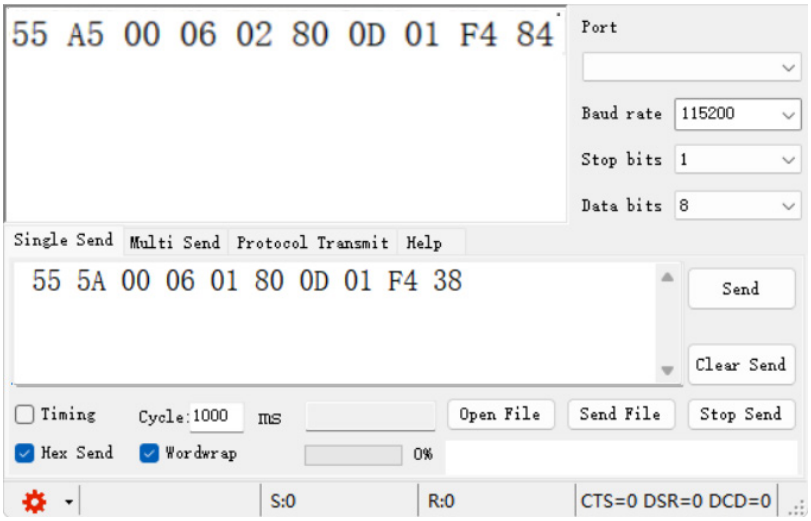
Motion detection threshold (≤1 m)	Read	55 5A 00 04 00 80 03 36	Default value 200
	Setting	55 5A 00 06 01 80 03 DATA1 DATA2 SUM	
	Receiver	55 A5 00 06 02 80 03 DATA1 DATA2 SUM	
Motion detection threshold (>1 m)	Read	55 5A 00 04 00 80 04 37	Default value 120
	Setting	55 5A 00 06 01 80 04 DATA1 DATA2 SUM 55	
	Receiver	A5 00 06 02 80 04 DATA1 DATA2 SUM	
Presence detection threshold (≤1 m)	Read	55 5A 00 04 00 80 09 3C	Default value 300
	Setting	55 5A 00 06 01 80 09 DATA1 DATA2 SUM 55	
	Receiver	A5 00 06 02 80 09 DATA1 DATA2 SUM	
Presence detection threshold (>1 m)	Read	55 5A 00 04 00 80 0A 3D	Default value 300
	Setting	55 5A 00 06 01 80 0A DATA1 DATA2 SUM 55	
	Receiver	A5 00 06 02 80 0A DATA1 DATA2 SUM	
Minimum detection distance (cm)	Read	55 5A 00 04 00 80 0C 3F	Default value 10
	Setting	55 5A 00 06 01 80 0C DATA1 DATA2 SUM	
	Receiver	55 A5 00 06 02 80 0C DATA1 DATA2 SUM	
Maximum motion detection distance (cm)	Read	55 5A 00 04 00 80 0D 40	Default value 600
	Setting	55 5A 00 06 01 80 0D DATA1 DATA2 SUM	
	Receiver	55 A5 00 06 02 80 0D DATA1 DATA2 SUM	
Maximum presence detection distance (cm)	Read	55 5A 00 04 00 80 0E 41	Default value 450
	Setting	55 5A 00 06 01 80 0E DATA1 DATA2 SUM	
	Receiver	55 A5 00 06 02 80 0E DATA1 DATA2 SUM	

OUT output level holding time (ms)	Read	55 5A 00 04 00 80 14 47	Default value 20000
	Setting	55 5A 00 06 01 80 14 DATA1 DATA2 SUM 55	
	Receiver	A5 00 06 02 80 14 DATA1 DATA2 SUM	
OUT indication mode	Read	55 5A 00 04 00 80 15 48	0x00 High level indication indicate body;0x01 Low level indication
	Setting	55 5A 00 05 01 80 15 DATA1 SUM	
	Receiver	55 A5 00 05 02 80 15 DATA1 SUM	

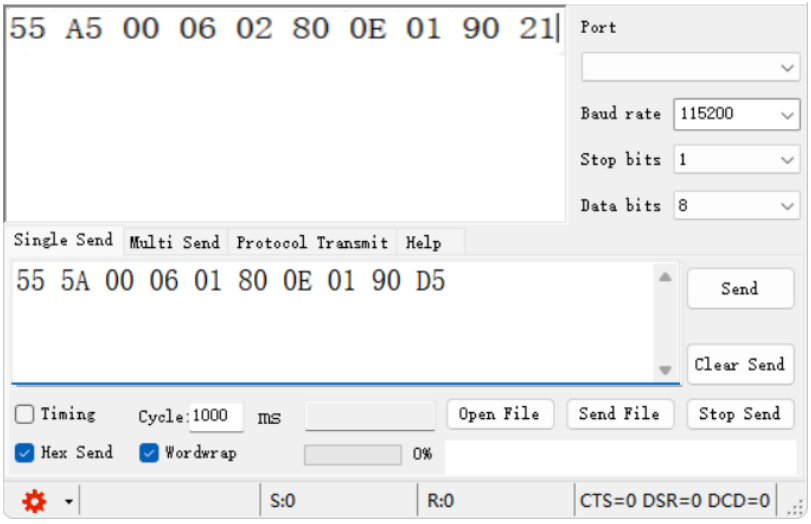
Example 2: Setting radar Parameter

If we want to set the radar's motion detection distance to 5 meters, presence detection distance to 4 meters, and the high level output delay time after sensing is 5 seconds: Then the serial port sends information: 55 5A 00 06 01 80 0D 01 F4 38. (For the specific meaning of each bit, please refer to the previous frame structure definition.)

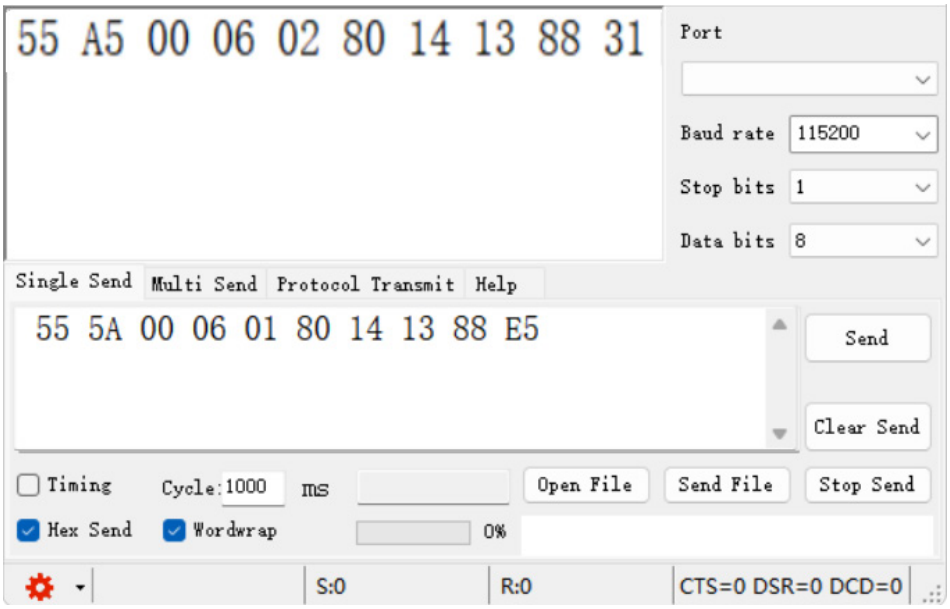
Serial port returns data information: 55 A5 00 06 02 80 0D 01 F4 84, Indicates that the motion detection distance has been set to 5 meters.



The serial port sends information: 55 5A 00 06 01 80 0E 01 90 D5.
Then serial port returns information: 55 A5 00 06 02 80 0E 01 90 21, Indicates that the presence detection distance has been set to 4 meters.



The serial port sends information: 55 5A 00 06 01 80 14 13 88 E5,
Then serial port returns information: 55 A5 00 06 02 80 14 13 88 31, Indicates that the high level holding time of the sensing output is set to 5 seconds.

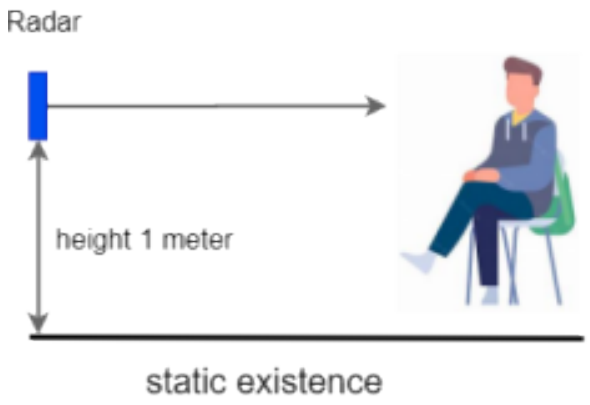


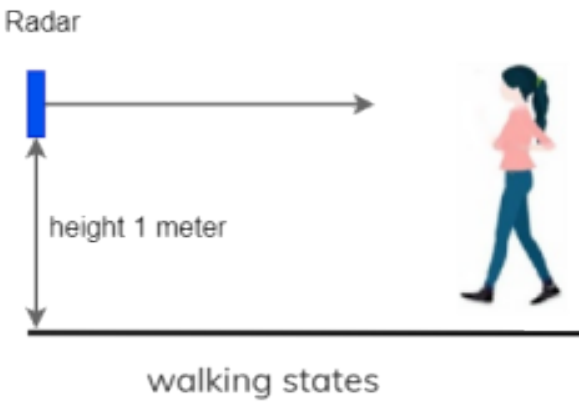
After the setting is completed, send the command: 55 5A 00 04 01 20 04 D8 to save the configuration; otherwise, the settings will be lost after powering off.

7 RADAR INSTALLATION AND TESTING

7.1 Test Application Scenario: Wall Mount

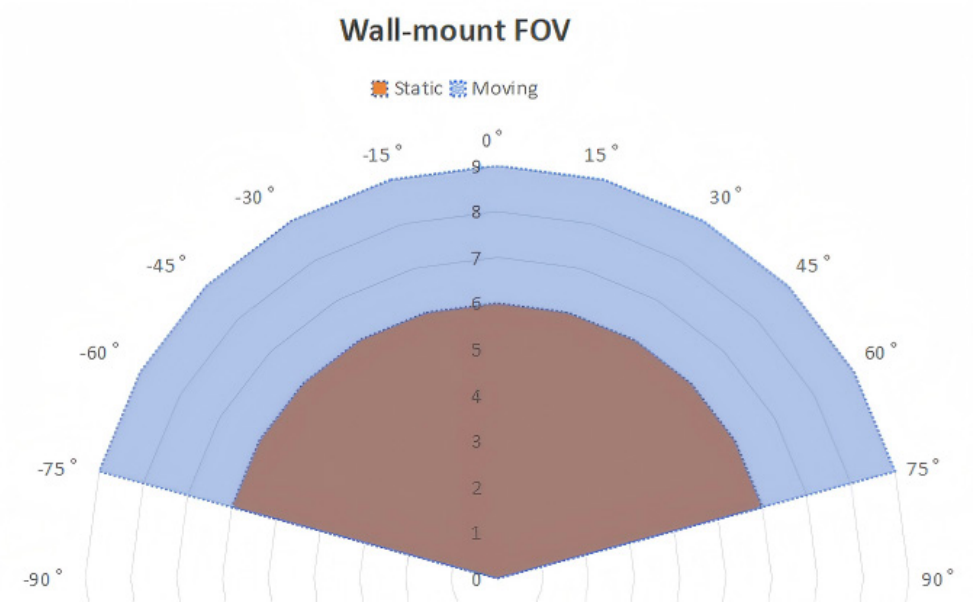
When testing wall mount installation, the installation height is about 1 meter, and the coverage range is tested in both sitting and walking states.





7.1.1 Reference Coverage

The following figure shows the wall mount coverage of the radar in the static state (orange area) and the moving state (blue area) under the default configuration for reference. Users can directly use the default mode for testing.



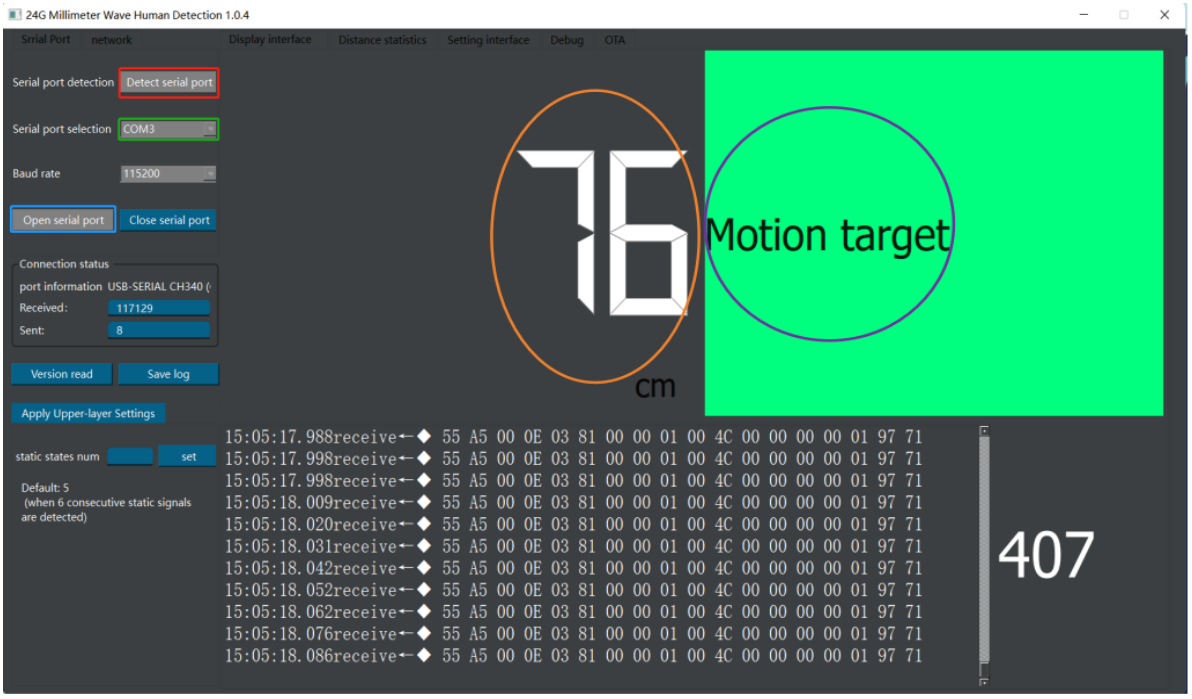
8 USE OF UPPER COMPUTER

MinewSemi also provides the upper computer of ME73MS01, which allows users to quickly configure and test the module performance. The following is the instructions for using the upper computer.

1)Use USB to TTL to power the radar with 5V voltage, then open "24G Millimeter Wave Human Detection" ;

2)Click Serial Port Detection - Serial Port Selection - Open Serial Port. The display interface will show the distance value and status.

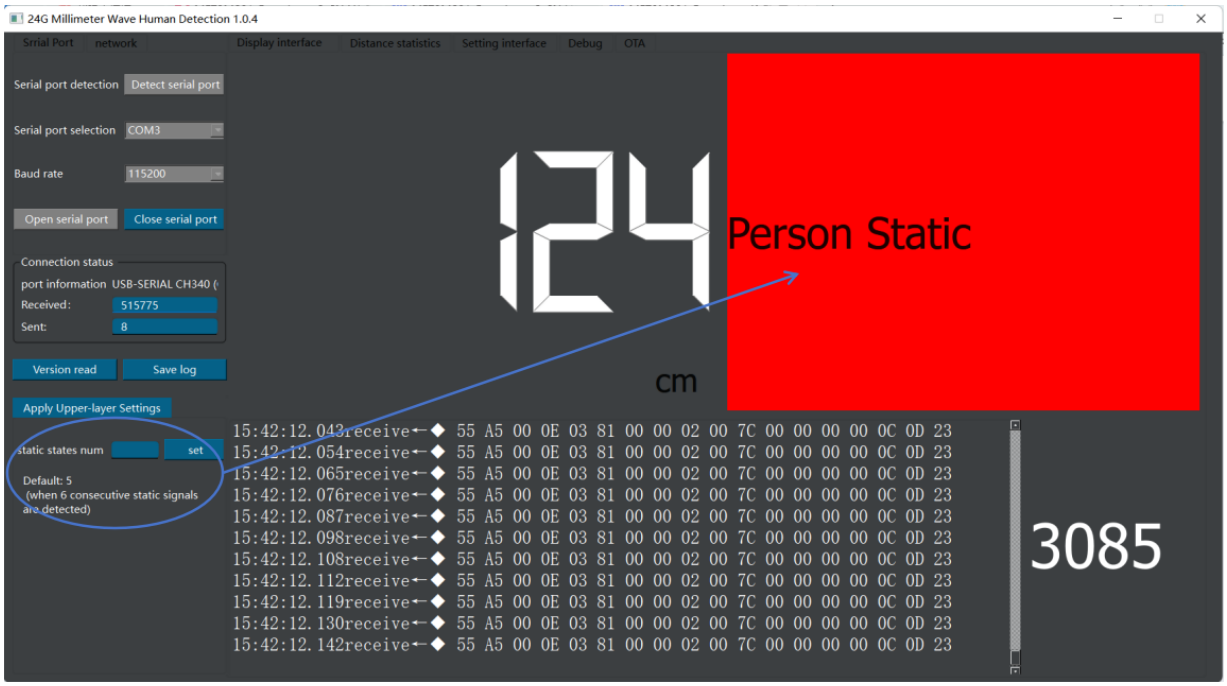
See the picture below:



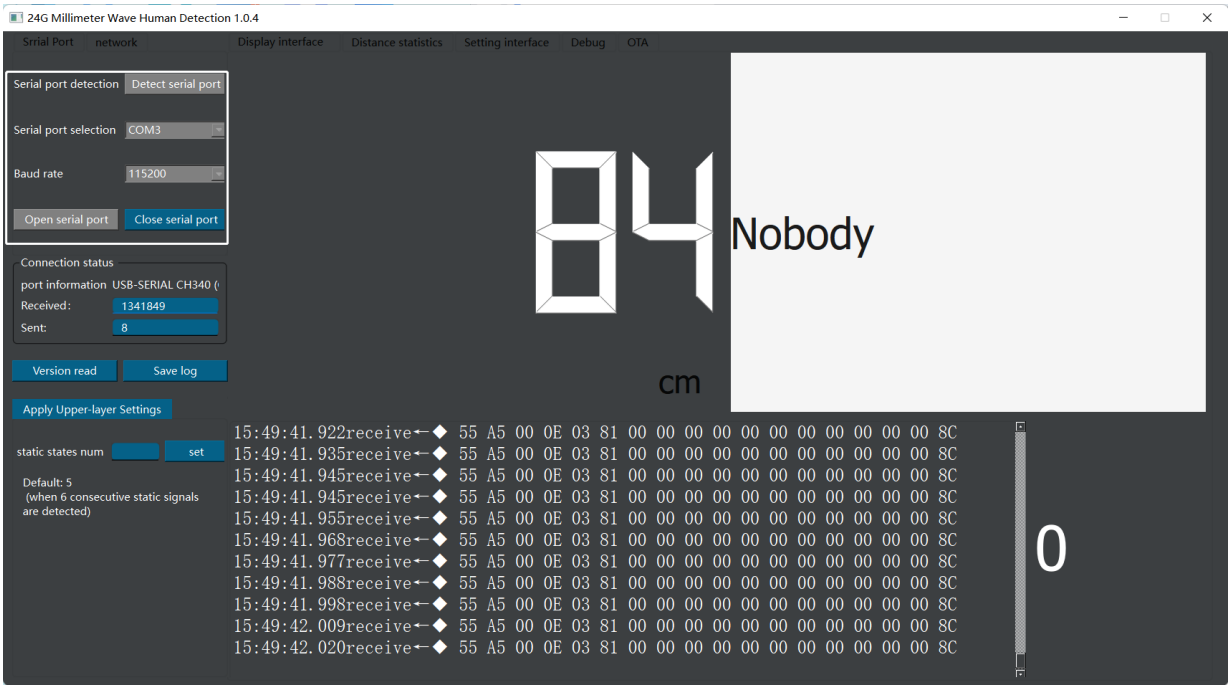
3)Application layer settings: This function is mainly used to configure the state transitions between motion detected, stationary presence, and no presence.

In the stationary presence count window, enter an integer greater than 2 and click Set. When the host continuously receives the occ count equal to or greater than the configured value, it will display the stationary presence status.

For example, if the value is set to 10, the host must consecutively receive 10 occ counts before indicating a stationary presence. The default value on the host is 6.
(See the figure below)

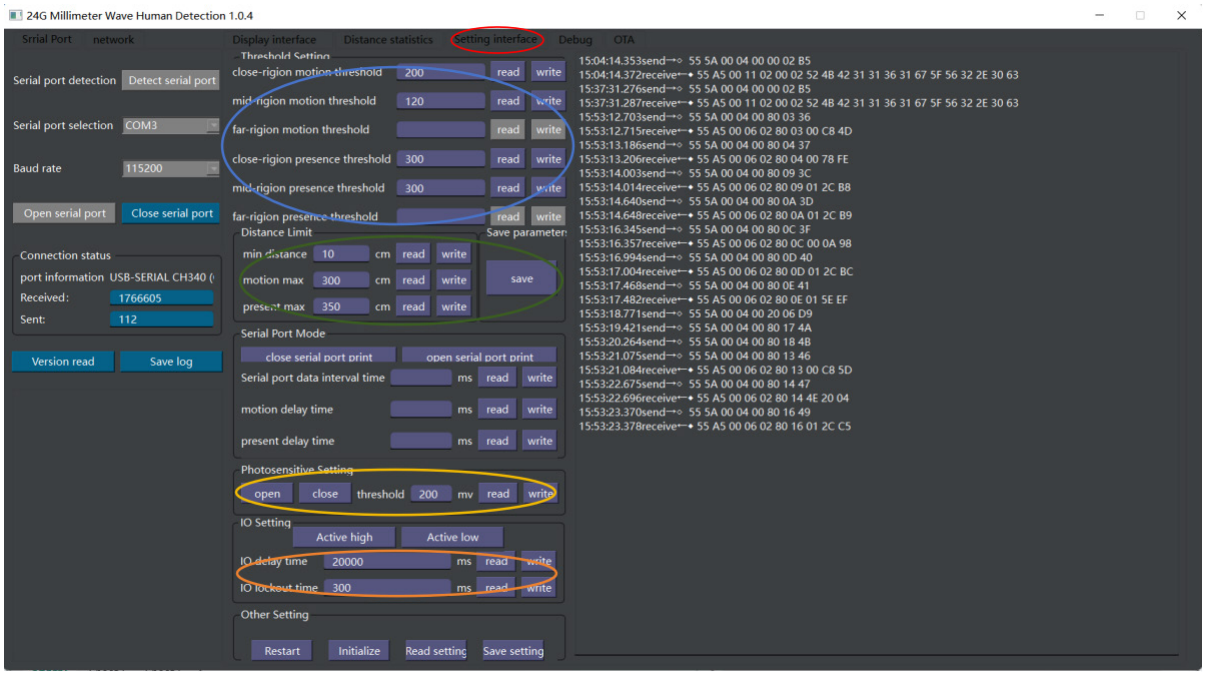


4)When the radar cannot detect the target, the upper computer outputs the Nobody state.

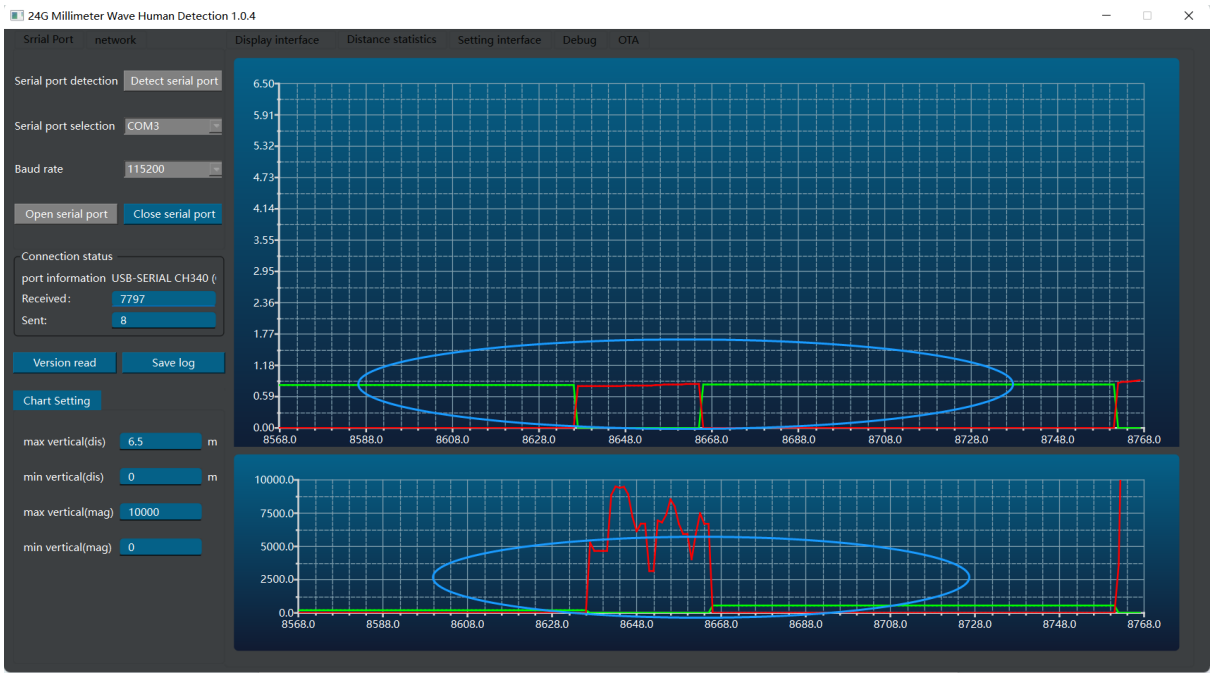


5)Click the setting interface window to enter the parameter setting interface. You can configure the module's sensitivity, detection distance, light sensitivity threshold, delay, etc. You can directly enter the value in the command box and click Write to modify the module parameters. In the sensitivity setting column, the close-range motion/presence sensitivity corresponds to the setting within 1 meter, the medium-range motion/presence sensitivity corresponds to the setting outside 1 meter, and the long-distance column is not open yet. For detailed parameter descriptions, see the command description in the previous text.

After modifying the parameters, click the Save button to save. (See picture below)



6)Click the distance statistics window to display the distance and signal strength curve in real time. The curve above the distance statistics window is the real-time distance curve. The red curve represents the distance of a stationary target, and the green curve represents the distance of a moving target. The lower window displays the real-time signal strength curve. The red curve represents the energy value of a stationary target, and the green curve represents the energy value of a moving target. (See picture below)



9 PRECAUTIONS

1.Avoid metal or other objects that hinder electromagnetic wave transmission in front of the module to block the antenna during installation;

2.The returned spectrum energy and parameter settings will be different for different housing materials and different distances between the module and the inner surface of the housing, and need to be fine-tuned according to actual conditions. It is generally recommended that the module be 5-6mm away from the housing, which can be adjusted according to actual measurements.

3.We recommend that users test the module according to the default settings first. If the effect is not as expected, the housing structure can be sent to the original factory, which will test and adjust a reference setting.

4.It is recommended to use ABS and other materials for the housing, because the human body radar is a very sensitive module. If a large attenuation material is used for the housing, it may affect the detection.

5.If the person being tested is sitting with his back or side facing the radar, the sensing effect will decrease. Because when the back is facing the side facing the radar, the chest or abdomen caused by breathing cannot be detected.

6.Avoid objects such as air conditioner outlets and fans when installing. Vibrating devices and objects may be detected by the radar and judged as human presence.

7.Avoid strong reflective objects such as large metal areas during installation. Metal is a strong reflector of electromagnetic waves, which may cause distortion of the received signal.

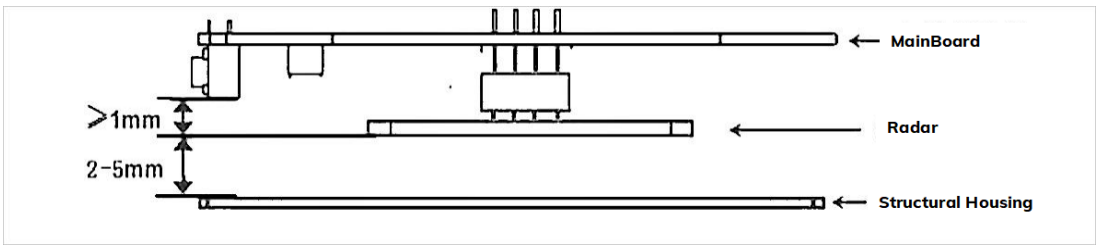
8.When multiple modules are installed and used at the same time, the distance between modules should be greater than 0.5 meters, and antennas of different modules should not be facing each other.

9.The module is used in ceiling mount, so the output detection distance has some errors compared to the straight line test. The FOV given in the manual is only for our test environment. The actual FOV may deviate due to different actual scene environments or factors such as the housing.

10. If you need more technical support, please contact sales.

10 HOUSING LAYOUT AND WELDING REQUIREMENTS

- It is recommended that the gap between the module antenna surface and the inner surface of the housing be 2~5mm. The housing material cannot be metal or metal-plated paint materials. The housing is recommended to be PC, ABS. The material thickness is preferably 2~3mm.
- PCBA: The height of the radar patch needs to be kept ≥ 1mm higher than other devices. When patching the PCBA, do not contaminate the chip. The chip must be flat and not warped.
- Housing detection surface: Non-metallic housing, needs to be flat to avoid bending, which affects the performance of the entire scanning area.



Layout diagram of antenna and housing

11 STORAGE CONDITIONS

- **Please use this product within 6 months after signing the receipt.**
  - This product should be stored without opening the package at an ambient temperature of 5~35°C and a humidity of 20~70%RH.
  - This product should be left for more than 6 months after receipt and should be confirmed before use.
  - The product must be stored in a non-corrosive gas (CI2, NH3, SO2, NOx, etc.).
  - To avoid damaging the packaging material, do not apply any excessive mechanical shocks, including but not limited to sharp objects adhering to the packaging material and product dropping.

- **This product is suitable for MSL2 (based on JEDEC standard J-STD-020).**
  - After opening the package, the product must be stored at ≤30°C/<60%RH. It is recommended to use the product within 3-6 months after opening the package.
  - When the color of the indicator in the package changes, the product should be baked before welding.

- **Baking is not required for one year if exposure is limited to <30°C and 60%RH. Refer to MSL2 for exposure criteria for moisture sensitivity level. If exposed to (≥168h@85°C/60%RH) conditions or stored for more than one year, recommended baking conditions.**
  1. 120 +5/-5°C, 8 hours, 1 time
  Products must be baked individually on heat-resistant trays because the materials (base tape, reel tape, and cover tape) are not heat-resistant, and the packaging material may be deformed at temperatures of 120℃;
  2、90℃ +8/-0℃, 24hours, 1times
  The base tape can be baked together with the product at this temperature. Please pay attention to the uniformity of heat.

12 HANDLING CONDITIONS

• Be careful in handling or transporting products because excessive stress or mechanical shock may break products.
• Handle with care if products may have cracks or damages on their terminals. If there is any such damage, the characteristics of products may change. Do not touch products with bare hands that may result in poor solder ability and destroy by static electrical charge.

13 QUALITY

Cognizant of our commitment to quality, we operate our own factory equipped with state-of-the-art production facilities and a meticulous quality management system. We hold certifications for ISO9001, ISO14001, ISO27001, OHSA18001, BSCI.

Every product undergoes stringent testing, including transmit power, sensitivity, power consumption, stability, and aging tests. Our fully automated module production line is now in full operation, boasting a production capacity in the millions, capable of meeting high-volume production demands.

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15 RELATED DOCUMENTS

- MinewSemi_Product_Naming_Reference_Manual
  https://en.minewsemi.com/file/MinewSemi_Product_Naming_Reference_Manual_EN.pdf
- MinewSemi_Connectivity_Module_Catalogue
  https://en.minewsemi.com/file/MinewSemi_Connectivity_Module_Catalogue_EN.pdf

For product change notifications and regular updates of Minewsemi documentation, please register on our website: **www.minewsemi.com**

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